MATH 10 - Linear Algebr	ra	Fall 2019
Ch 1 Euclidean Spaces		In-class Assignment $#4$
$\S1.5, 1.6, 1.7, 1.8$		Dr. Jorge Basilio
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## Activity 1: Definitions

Write the precise definitions of the following terms:

- (a) a **linearly dependent** set of vectors  $S = {\vec{v}_1, \ldots, \vec{v}_k}$ .
- (b) a **linearly independent** set of vectors  $S = {\vec{v}_1, \ldots, \vec{v}_k}$ .
- (c) a subspace W of  $\mathbb{R}^n$ . Also, the trivial subspaces of  $\mathbb{R}^n$ .
- (d) a **basis** of a non-zero subspace W of  $\mathbb{R}^n$ .
- (e) Given a finite set X, the **cardinality** of X, card(X).
- (f) the **dimension** of a subspace W of  $\mathbb{R}^n$ .
- (g) the four fundamental subspaces of a matrix  $A_{m \times n}$ . Be sure to indicate the ambient spaces.
- (h) The **rank** and **nullity** of a matrix  $A_{m \times n}$ .

## Activity 2: Proof

We would like to prove the following fact:

A non-empty subset  $U \subseteq \mathbb{R}^n$  is a subspace of  $\mathbb{R}^n$  if and only if U = Span(S) for some non-empty subset S of  $\mathbb{R}^n$ .

- (a)  $(\Longrightarrow)$  Give a statement of the "Forward direction".
- (b) ( $\Leftarrow$ ) Give a statement of the "Backward direction".
- (c) Which direction is the "easy" direction to prove? Explain why, or give a proof.
- (d) Prove the other direction.

## Activity 3: Computation

Consider the augmented matrix:

$$\begin{bmatrix} A|\vec{b} \end{bmatrix} = \begin{bmatrix} 3 & -5 & 1 & -3 & -3 & 4 & | & 3\\ 4 & -6 & 4 & -2 & -3 & 2 & | & 8\\ 1 & -5 & -13 & -11 & -6 & 18 & | & -19\\ -2 & 4 & 2 & 4 & 2 & 2 & | & 0\\ 26 & -38 & 30 & -10 & -23 & 48 & | & 48 \end{bmatrix}; \text{ RREF: } R = \begin{bmatrix} 1 & 0 & 7 & 4 & 0 & 5 & | & 8\\ 0 & 1 & 4 & 3 & 0 & 7 & | & 3\\ 0 & 0 & 0 & 0 & 1 & -8 & | & 2\\ 0 & 0 & 0 & 0 & 0 & 0 & | & 0\\ 0 & 0 & 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

- (a) Find a **basis** for the rowspace of A, RS(A), using the information in R. (Reminder: A is only the first 6 columns)
- (b) Find a **basis** for the columnspace of A, CS(A).
- (c) Find a **basis** for the nullspace of A, NS(A). (You can use the "sight-seeing" mentioned in the textbook if you wish. Just be careful with free variables!)
- (d) Express the non-basis columns of A as linear combinations of the basis vectors that you chose in part (b). (*Hint: what I call "magic"*)
- (e) Describe all the solutions to  $A\vec{x} = \vec{b}$  in the form  $\vec{x}_P + \vec{x}_h$  where  $\vec{x}_P$  is a particular solution, and  $\vec{x}_h$  represents solutions to the homogenous system.
- (f) Express row 3 of A as a linear combination of your basis in part (a).

Now, you are also given that  $RREF(A^{\top})$  is R' and:

(Notice we don't include  $\vec{b}$  in the transpose.)

- (g) Find a **basis** for the nullspace of  $A^{\top}$ ,  $NS(A^{\top})$ .
- (h) State the Dimension Theorem for Matrices, in general. (Don't forget it is both parts!)
- (i) State the rank and the nullity of A and also  $A^{\top}$ , and verify the Dimension Theorem for A and  $A^{\top}$ .
- (j) Now, use the information in R' to find *another* basis for RS(A). (Hint: the rows of A become the columns of  $A^{\top}$ .)
- (k) Express the 3rd row of A as a linear combination of the basis you found in part (j). (You'll need to set-up a SOE and use GJE to arrive at your answer)
- (1) What is the nullity of  $A^{\top}$ ? Explain how you got your answer. (*Hint: Warning! Do not find*  $RREF(A^{\top})$ . You don't need it!)