

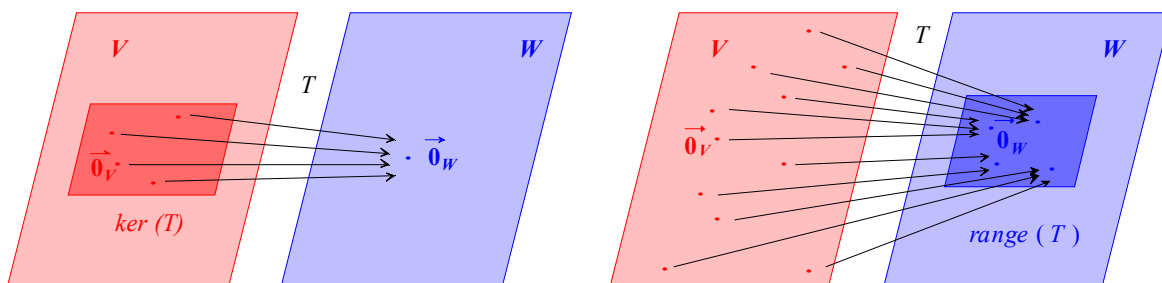
## 3.7 One-to-One and Onto

### Linear Transformations ;

### Compositions of

### Linear Transformations

Review:



$$\ker(T) = \left\{ \vec{v} \in V \mid T(\vec{v}) = \vec{0}_W \right\}$$

$$\text{range}(T) = \left\{ \vec{w} \in W \mid \vec{w} = T(\vec{v}) \text{ for some } \vec{v} \in V \right\}$$

## One-to-One Transformations

**Definition:** We say that a linear transformation  $T : V \rightarrow W$  is *one-to-one* or *injective* if the image of different vectors from the domain are different vectors from the codomain:

$$\text{If } \vec{v}_1 \neq \vec{v}_2 \text{ then } T(\vec{v}_1) \neq T(\vec{v}_2).$$

We again say that  $T$  is an *injection* or an *embedding*.

**Theorem:** A linear transformation  $T : V \rightarrow W$  is *one-to-one* if and only if the only way two vectors from the domain have the same image in the codomain is for them to be the same vector to begin with:

$$\text{If } T(\vec{v}_1) = T(\vec{v}_2) \text{ then } \vec{v}_1 = \vec{v}_2.$$

In other words, the only solution to  $T(\vec{v}_1) = T(\vec{v}_2)$  is  $\vec{v}_1 = \vec{v}_2$ .

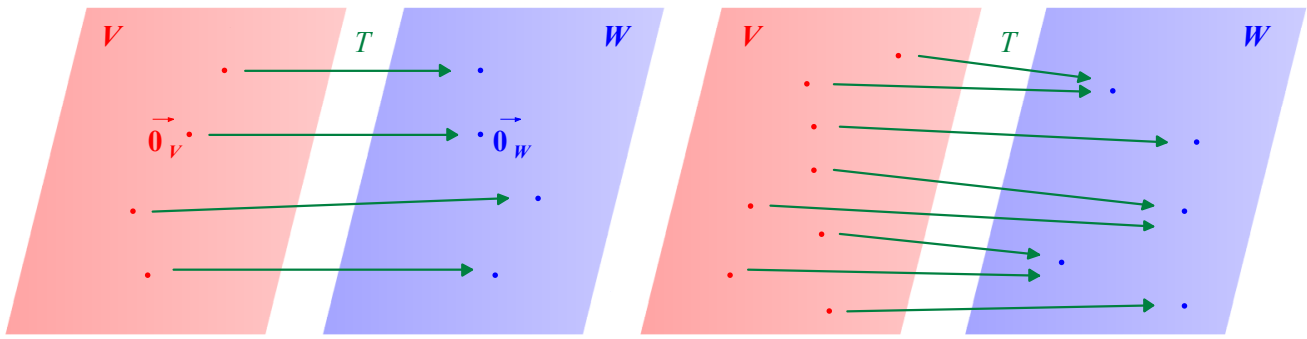
**Theorem:** A linear transformation  $T : V \rightarrow W$  is one-to-one *if and only if*  $\ker(T) = \{\vec{0}_V\}$ .

# Onto Transformations

**Definition:** We say that a linear transformation  $T : V \rightarrow W$  is **onto** or **surjective** if the range of  $T$  is **all** of  $W$  :

$$\text{range}(T) = W.$$

Since  $\text{rank}(T) = \dim(\text{range}(T))$ , we can also say that  $T$  is **onto if and only if**  $\text{rank}(T) = \dim(W)$ , in the case when  $W$  is **finite dimensional**.



**one-to-one**  $\Leftrightarrow$   
 $\ker(T) = \{ \vec{0}_V \}$

**onto**  $\Leftrightarrow$   
 $\text{range}(T) = W$

## *Finding the Kernel and Range Using $[T]_{B,B'}$*

The information provided by  $[T]_{B,B'}$  and its rref simply needs to be *decoded* with respect to the appropriate basis: we use  $B$  for  $\ker(T)$  and  $B'$  for  $\text{range}(T)$ .

**Theorem:** Suppose that  $T : V \rightarrow W$  is a linear transformation, with  $\dim(V) = n$  and  $\dim(W) = m$ , both finite-dimensional vector spaces. Let  $B = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  be a basis for  $V$ , and let  $B' = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_m\}$  be a basis for  $W$ . Let us construct the  $m \times n$  matrix  $[T]_{B,B'}$  as we did in the previous Section, and let  $R$  be the rref of  $[T]_{B,B'}$ . Suppose that:

$$\{\vec{z}_1, \vec{z}_2, \dots, \vec{z}_k\} \subset \mathbb{R}^n$$

is the basis that we obtain for  $\text{nullspace}([T]_{B,B'})$  using  $R$ , as we did in Chapter 2.

By the Uniqueness of Representation Property, we know that there exists  $\vec{u}_i \in V$  so that  $\langle \vec{u}_i \rangle_B = \vec{z}_i$  for every  $i = 1 \dots k$ .

We conclude that the set  $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k\} \subset V$  is a **basis** for  $\ker(T)$ .

As usual, if there are no free variables in  $R$ , then  $\text{nullspace}([T]_{B,B'}) = \{\vec{\mathbf{0}}_n\}$ , and consequently,  $\ker(T) = \{\vec{\mathbf{0}}_V\}$ .

Similarly, the set of original columns:

$$\{\vec{c}_{i_1}, \vec{c}_{i_2}, \dots, \vec{c}_{i_r}\} \subset \mathbb{R}^m$$

from  $[T]_{B, B'}$  corresponding to the leading 1's of  $R$  form a basis for  $\text{columnspace}([T]_{B, B'})$  as we found in Chapter 2, and there exists  $\vec{d}_j \in W$  so that  $\langle \vec{d}_j \rangle_{B'} = \vec{c}_{i_j}$  for every  $j = 1 \dots r$ .

We conclude that the set  $\{\vec{d}_1, \vec{d}_2, \dots, \vec{d}_r\} \subset W$  is a *basis* for  $\text{range}(T)$ .

If  $T$  is the zero transformation, then  $\text{range}(T) = \{\vec{\mathbf{0}}_W\}$ .

## *The Dimension Theorem for Abstract Vector Spaces*

### *Theorem — The Dimension Theorem:*

Let  $T : V \rightarrow W$  be a linear transformation, and suppose that  $V$  is *finite dimensional* with  $\dim(V) = n$ . Then, both  $\ker(T)$  and  $\text{range}(T)$  are finite dimensional, and we can define:

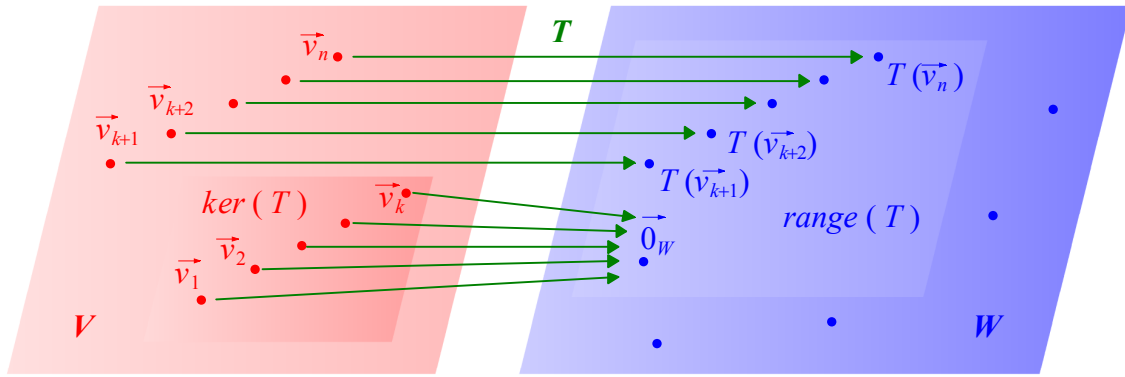
$$\text{rank}(T) = \dim(\text{range}(T)), \text{ and}$$

$$\text{nullity}(T) = \dim(\ker(T)).$$

Furthermore, these quantities are related by the equation:

$$\begin{aligned} & \text{rank}(T) + \text{nullity}(T) \\ &= n = \dim(V) = \dim(\text{domain of } T). \end{aligned}$$





## Idea of the Proof

Let's say  $\text{nullity}(T) = k$ .

$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  a basis for  $\ker(T)$

Use the *Extension Theorem*:

$B = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k, \vec{v}_{k+1}, \vec{v}_{k+2}, \dots, \vec{v}_n\}$  a basis for  $V$ .

Examine  $\text{range}(T)$  :

$$\begin{aligned}\vec{v} &= c_1\vec{v}_1 + c_2\vec{v}_2 + \cdots + c_k\vec{v}_k + \\ &\quad c_{k+1}\vec{v}_{k+1} + c_{k+2}\vec{v}_{k+2} + \cdots + c_n\vec{v}_n.\end{aligned}$$

$$\begin{aligned}T(\vec{v}) &= c_1T(\vec{v}_1) + c_2T(\vec{v}_2) + \cdots + c_kT(\vec{v}_k) + \\ &\quad c_{k+1}T(\vec{v}_{k+1}) + c_{k+2}T(\vec{v}_{k+2}) + \cdots + c_nT(\vec{v}_n) \\ &= c_{k+1}T(\vec{v}_{k+1}) + c_{k+2}T(\vec{v}_{k+2}) + \cdots + c_nT(\vec{v}_n)\end{aligned}$$

This tells us that every vector in  $\text{range}(T)$  is . . . . .

Show that  $\{T(\vec{v}_{k+1}), T(\vec{v}_{k+2}), \dots, T(\vec{v}_n)\}$  is linearly independent:

$$d_{k+1}T(\vec{v}_{k+1}) + d_{k+2}T(\vec{v}_{k+2}) + \dots + d_nT(\vec{v}_n) = \vec{0}_W.$$

$$T(d_{k+1}\vec{v}_{k+1} + d_{k+2}\vec{v}_{k+2} + \dots + d_n\vec{v}_n) = \vec{0}_W.$$

Conclusion: the vector inside the parenthesis is in . . .

$$\begin{aligned} & d_{k+1}\vec{v}_{k+1} + d_{k+2}\vec{v}_{k+2} + \cdots + d_n\vec{v}_n \\ &= d_1\vec{v}_1 + d_2\vec{v}_2 + \cdots + d_k\vec{v}_k, \end{aligned}$$

$$\begin{aligned} & -d_1\vec{v}_1 - d_2\vec{v}_2 - \cdots - d_k\vec{v}_k + \\ & d_{k+1}\vec{v}_{k+1} + d_{k+2}\vec{v}_{k+2} + \cdots + d_n\vec{v}_n = \vec{0}_W \end{aligned}$$

Conclusion:

## Comparing Dimensions

**Theorem:** Suppose  $T : V \rightarrow W$  is a linear transformation of finite dimensional vector spaces. Then:

- a) if  $\dim(V) < \dim(W)$ , then  $T$  *cannot* be onto.
- b) if  $\dim(V) > \dim(W)$ , then  $T$  *cannot* be one-to-one.

## Compositions of Linear Transformations

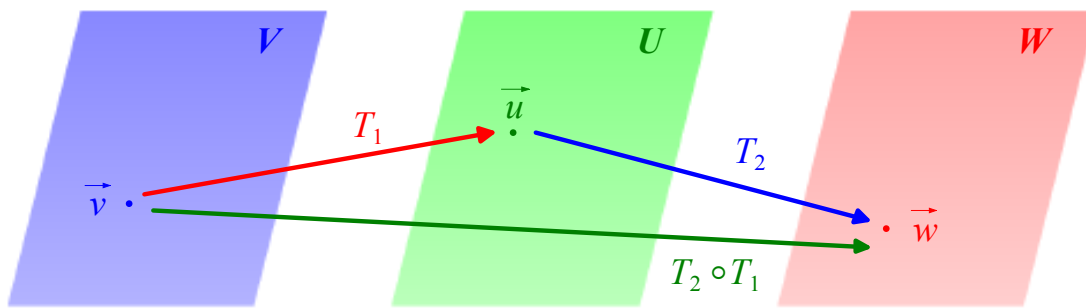
**Definition/Theorem:** Suppose  $T_1 : V \rightarrow U$ , and  $T_2 : U \rightarrow W$  are linear transformations. The *composition*:

$$T_2 \circ T_1 : V \rightarrow W$$

is again a linear transformation, with action given as follows:

Suppose  $\vec{v} \in V$ ,  $T_1(\vec{v}) = \vec{u} \in U$ , and  $T_2(\vec{u}) = \vec{w} \in W$ . Then:

$$(T_2 \circ T_1)(\vec{v}) = T_2(T_1(\vec{v})) = T_2(\vec{u}) = \vec{w}.$$



### The Composition of Two Linear Transformations

## The Matrix of a Composition

**Theorem:** Let  $T_1 : V \rightarrow U$  and  $T_2 : U \rightarrow W$  be linear transformations of finite dimensional vector spaces. Let  $B$  be a basis for  $V$ ,  $B'$  a basis for  $U$ , and  $B''$  a basis for  $W$ . Then:

$$[T_2 \circ T_1]_{B, B''} = [T_2]_{B', B''} \cdot [T_1]_{B, B'}$$

**Proof:**

$$B = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$$

$$B' = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k\}$$

$$B'' = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_m\}$$



$$\begin{aligned}
& [T_2 \circ T_1]_{B, B''} \\
&= Z \\
&= \left[ [(T_2 \circ T_1)(\vec{v}_1)]_{B''} \mid [(T_2 \circ T_1)(\vec{v}_2)]_{B''} \mid \right. \\
&\quad \left. \cdots [(T_2 \circ T_1)(\vec{v}_n)]_{B''} \right]
\end{aligned}$$

$$\begin{aligned}
& [T_2]_{B', B''} \\
&= X \\
&= \left[ [T_2(\vec{u}_1)]_{B''} \mid [T_2(\vec{u}_2)]_{B''} \mid \cdots \mid [T_2(\vec{u}_k)]_{B''} \right]
\end{aligned}$$

$$\begin{aligned}
& [T_1]_{B, B'} \\
&= Y \\
&= \left[ [T_1(\vec{v}_1)]_{B'} \mid [T_1(\vec{v}_2)]_{B'} \mid \cdots \mid [T_1(\vec{v}_n)]_{B'} \right]
\end{aligned}$$

## *Function Spaces Preserved by the Derivative*

*Example:* Find the matrix of the *second derivative*,  $D^2$ , applied to the function space:

$$V = \text{Span}(\{x^2 e^{4x}, xe^{4x}, e^{4x}\})$$