

What is Linear Algebra?

Dr. Basilio

Outline

Beauty & Importance

Vectors

Systems of Equations

Birth of Linear Algebra

Elimination

Back to Mathematician's vectors

What is Linear Algebra?

What is Linear Algebra? A Bird's Eye View

Dr. Jorge Eduardo Basilio

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Outline





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- Systems of Equations
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- What is Linear Algebra?

What is Linear Algebra? Beauty & Importance



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What is Linear Algebra?

• A beautiful subject ... why?

- real mathematical theory
- (likely) your first love of proofs (ok..exposure to proofs at least :P)
- moves effortlessly from lines, to planes, to hyperplanes, to n-dimensional space \mathbb{R}^n
- you'll learn to "see" 12-dimensional space
- Ditch geometry, but don't ditch geometry!
- theory with purpose! So many APPs (applications)
- Enormous importance! Maybe even greater than Calculus!

What is Linear Algebra? Beauty & Importance



- Economics: Leontief model of Economics (1950s Harvard professor \rightarrow won Nobel prize in Econ)
- Physics: so many! A few are...
 - vectors in 2D, 3D, and higher dimensions
 - Forces, Electrice Fields, Magnetic Fields, ...
 - Quantum Mechanics (uses ∞-dimensional LA)
- Data Science: stats + LA + Calc + programming
- Engineering:
- MATH duh!
 - most (all?) mathematical courses use LA in some way
- Before you can study the LAPs you need a solid understanding of linear algebra!



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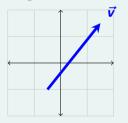
What is Linear Algebra?

We start with vectors. Vectors according to...

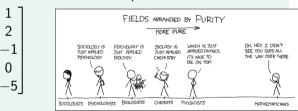
 $\vec{v} =$

Physicists

"something with a magnitude & direction"



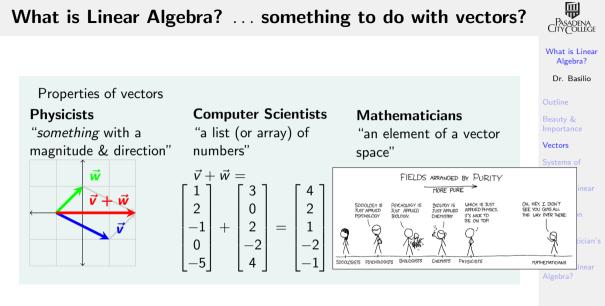
Computer Scientists "a list (or array) of numbers"



space"

Mathematicians

"an element of a vector



What is Linear Algebra? ... something to do with vectors?

Mathematician's view abstracts the properties shared by many different objects studied over a long period of time. So, mathematician's care **only** about structure of objects not superficially what they look like.

- Vectors live in vector spaces. Vector spaces are collections of objects that satisfy many properties. The most important are:
 - P(ℝ, ℝ) space of all polynomials
 - C([a, b], ℝ) space of all continuous functions
 - C[∞]([a, b], ℝ) space of all differentiable functions
 - $\ell_\infty(\mathbb{R})$ space of all sequences
 - space of all power series



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ℝⁿ
 ℂⁿ

• 7ⁿ

• **O**ⁿ

• $\mathbb{M}_{n \times n}$ - space of all $n \times n$ matrices

What is Linear Algebra? ... something to do with vectors?

Mathematician's care **only** about structure of objects not superficially what they look like.

- What do these examples have in common?
- Addition: there is a "natural" way to define how to add two objects
- Scalar Multiplication: there is a "natural" what to define what multiplying an object by a real number α
- Example: using computer scientist's concept of vector, we can define "addition" and "scalar multiplication" via components

$$\begin{bmatrix} 1\\2\\-1\\0 \end{bmatrix} + \begin{bmatrix} 3\\0\\2\\-2 \end{bmatrix} = \begin{bmatrix} 4\\2\\1\\-2 \end{bmatrix} \text{ and } \alpha \cdot \begin{bmatrix} 4\\2\\1\\-2 \end{bmatrix} = \begin{bmatrix} 4\alpha\\2\alpha\\\alpha\\-2\alpha \end{bmatrix}$$



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What is Linear Algebra? ... matrices?

Mathematician's care **only** about structure of objects not superficially what they look like.

- But isn't linear algebra ↔ Matrix Algebra?
- Addition: there is a "natural" way to define how to add two objects
- Scalar Multiplication: there is a "natural" what to define what multiplying an object by a real number α
- Example: For matrices we define "addition" and "scalar multiplication" via components as well

$$\begin{bmatrix} 1 & -7\\ 2 & 8\\ -1 & -3\\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 3 & 0\\ 0 & 1\\ 2 & -5\\ -2 & 6 \end{bmatrix} = \begin{bmatrix} 4 & 6\\ 2 & 9\\ 1 & -8\\ -2 & 8 \end{bmatrix} \text{ and } \alpha \cdot \begin{bmatrix} 4 & 6\\ 2 & -1\\ 1 & -3\\ -2 & 8 \end{bmatrix} = \begin{bmatrix} 4\alpha & 6\alpha\\ 2\alpha & -\alpha\\ \alpha\\ -2\alpha & 8\alpha \end{bmatrix}$$



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In many ways, all of linear algebra boils down to solving a system of equations.

•
$$\begin{cases} x + 2y + 3z = 4 \\ -x + y - 5z = 0 \\ 2x - y - z = -1 \end{cases} \longleftrightarrow \begin{bmatrix} 1 & 2 & 3 \\ -1 & 1 & -5 \\ 2 & -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -1 \end{bmatrix}$$

$$\iff x \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + y \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} + z \begin{bmatrix} 3 \\ -5 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -1 \end{bmatrix}$$



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System of equations. A simple example.

•
$$\begin{cases} x - y = -2 \\ x + 2y = 1 \end{cases} \iff \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \iff \boxed{A\vec{x} = \vec{b}}$$

• "row picture"
$$\begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$
 intersection of two lines
• "column picture" $x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ linear combinations



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System of equations. A simple example.

•
$$\begin{cases} x - y = -2 \\ x + 2y = 1 \end{cases} \iff \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \iff \boxed{A\vec{x} = \vec{b}}$$

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System of equations. A simple example.
•
$$\begin{cases} x - y = -2 \\ x + 2y = 1 \end{cases} \iff \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \iff \boxed{A\vec{x} = \vec{b}}$$
• "column picture" $x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ linear combinations

Geometry of linear combinations...



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System of equations.

- Okay, that was easy. So what?
- We need to solve LARGE systems.
- A system with *n* variables and *n* unknowns:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2 \\ \vdots & \vdots & \vdots & \vdots & = \vdots \\ a_{n1}x_1 + a_{n2}x_2 + a_{n3}x_3 + \dots + a_{nn}x_n = b_n \end{cases} \Leftrightarrow \boxed{A\vec{x} = \vec{b}} \\ \Leftrightarrow \boxed{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} \end{bmatrix}} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

Note: $n = 1000$ is considered "small" nowadays



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System of equations.

• A system with *n* variables and *n* unknowns:

• "Row picture" $\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$

Row picture = intersection of n hyperplanes

• "Column picture"
$$x_1 \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix} + x_2 \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{n2} \end{bmatrix} + \dots + x_n \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{nn} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

Bow picture = what linear combination of columns equals \vec{b} ?



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Recall the simple example.

•
$$\begin{cases} x - y = -2 \\ x + 2y = 1 \end{cases} \iff \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \iff \boxed{A\vec{x} = \vec{b}}$$

• "column picture" $x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ linear combinations
• Notation: Let $\vec{v} = \text{Col } 1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\vec{w} = \text{Col } 2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, and $\vec{b} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$
• Recall: we found that $(-1)\vec{v} + (1)\vec{w} = \vec{b}$ (i.e. $x = -1$, $y = 1$).

The birth of linear algebra is to consider <u>ALL</u> possible linear combinations of \vec{v} and \vec{w} !!!!

That is, $\{x_1\vec{v} + x_2\vec{w} \mid x_1, x_2 \in \mathbb{R}\} = \operatorname{span}(\vec{v}, \vec{w})$



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The birth of linear algebra is to consider <u>ALL</u> possible linear combinations of \vec{v} and \vec{w} !!!!

That is, $\{x_1\vec{v} + x_2\vec{w} \mid x_1, x_2 \in \mathbb{R}\} = \operatorname{span}(\vec{v}, \vec{w})$

• Notation: Let
$$\vec{v} = \text{Col } 1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
, $\vec{w} = \text{Col } 2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, and $\vec{b} = \begin{bmatrix} a \\ b \end{bmatrix}$

- So, we can write $A = [\vec{v} | \vec{w}]$
- Can we solve this for any $a, b \in \mathbb{R}$?
- YES!
- Why? Because all linear combinations of \vec{v} and \vec{w} will fill the entire plane!!!
- Higher dimensions is much more interesting :-)



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To summarize:

• A major problem in linear algebra is to solve a system of equations:

$$A\vec{x} = \vec{b}$$

- This is the same thing as asking: when is \vec{b} a linear combination of the columns vectors of A (i.e. in the span)?
- This is solved using Gauss-Jordan elimination. A clever algorithm that's embarrassingly simple (in principle)



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- Next, we generalize our situation to systems of equations with an uneven number of equations and unknowns.
- If we let m = # equations and n = # unknowns, we'd like to study

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2 \\ \vdots & \vdots & \vdots & \vdots & = \vdots \\ a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n = b_m \end{cases} \iff \boxed{A\vec{x} = \vec{b}}$$

- New phenomena can occur now.
- **Imagine** What if we have two 5-dimensional vectors \vec{v} and \vec{w} . Can all their linear combinations fill-up all of 5-dimensional space?
- NO! There's too few vectors
- What about five, 5-dimensional vectors? It depends....they must all "live in their separate planes"...



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- New phenomena can occur now.
- Imagine What if we have two 5-dimensional vectors \vec{v} and \vec{w} . Can all their linear combinations fill-up all of 5-dimensional space?
- NO! There's too few vectors
- What about five, 5-dimensional vectors? It depends....they must all "live in their separate planes"...
- This introduces the important idea of independence. That is, we say a collection of vectors are independent if they "fill up" space as much as possible (a more precise definition will be given later).
- Remarkably, all this information is encoded in the matrix A associated to the SOE.



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- Remarkably, all this information is encoded in the matrix A associated to the SOE.
- By studying the structure of *A*, we can answer many fundamental questions related to a SOE.
- There's four fundamental "subspaces" associated to A
 - Column Space (all linear combinations of columns of A)
 - Row Space (all linear combinations of rows of A)
 - Null space of A
 - Null space of A^T



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Gauss-Jordan Elimination

- Meanwhile: almost every problem in linear algebra is solved (one way or another with) Gauss-Jordan Elimination (GJE).
- The method of GJE is used for
 - Checking if a list of vectors are independent
 - Solving SOEs: $A\vec{x} = \vec{b}$
 - Checking if a vector \vec{b} is in the span of of a list of other vectors (= space of all linear combinations)
 - Finding the column space of a matrix
 - Finding the row space of a matrix
 - Finding the rank of a matrix
 - Basically everything in Linear Algebra :-)



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What is Linear Algebra?

Back to Mathematician's vectors

Recall: the mathematician's view of "vectors:" objects you can ADD and scalar multiply. We can do that with matrices! Addition

 $\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} & b_{13} & \cdots & b_{1n} \\ b_{21} & b_{22} & b_{23} & \cdots & b_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & b_{n3} & \cdots & b_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & a_{13} + b_{13} & \cdots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & a_{23} + b_{23} & \cdots & a_{2n} + b_{2n} \\ \vdots & \vdots & \vdots & \ddots & a_{2n} + b_{2n} \\ \vdots & \vdots & \vdots & \ddots & a_{2n} + b_{2n} \\ a_{n1} + b_{n1} & a_{n2} + b_{n2} & a_{n3} + b_{n3} & \cdots & a_{nn} + b_{nn} \end{bmatrix}$



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Recall: the mathematician's view of "vectors:" objects you can ADD and scalar multiply. We can do that with matrices! Scalar Multiplication

α	a 11	<i>a</i> ₁₂	a_{13}	• • •	a _{1n}	=	αa_{11}	αa_{12}			
	a ₂₁	a ₂₂	a ₂₃	• • •	a _{2n}		αa_{21}	$lpha a_{22}$	=-		
	÷	÷	÷		÷		1	÷	÷		:
	a _{n1}	a _{n2}	a _{n3}	• • •	ann		αa_{n1}	αa_{n2}	αa_{n3}	• • •	αa_{nn}



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Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

What is Linear Algebra?

Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

- We've briefly discussed vectors and vector spaces (the set/collection of all vectors).
- Notation: \vec{v} a vector. V the vector space that collects all vectors. We can write $\vec{v} \in V$.
- The structure of V is easy to describe:
 - "closure under addition": if $\vec{v}, \vec{w} \in V$, then $\vec{v} + \vec{w} \in V$
 - "closure under scalar multiplication:" if $\vec{v}, \vec{w} \in V$, and $a, b \in \mathbb{R}$ are arbitrary, then $a\vec{v} + b\vec{w} \in V$
- The second bullet is what "linear structure" means in an abstract sence.



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What is Linear Algebra?

Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

- The other major goal, once we understand what vector spaces are (and have studied many examples), is to study maps (or functions) between two vector spaces.
- Notation: $T: V \to W$. If $\vec{v} \in V$, then $T(\vec{v}) \in W$
- T because we want to study "linear transformations"
- The structure of T is easy to describe:
 - "additive structure:" if $\vec{v}, \vec{w} \in V$, then $T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w})$
 - "homogeneous structure:" if $\vec{v} \in V$ and $a \in \mathbb{R}$, then $|T(a\vec{v}) = aT(\vec{v})|$



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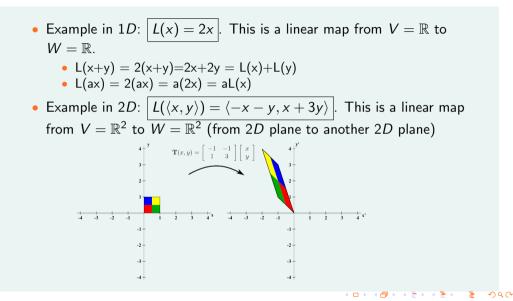
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Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

There's so much more to this story!

- Add more structure: inner-products (measure length of vectors and angles). Can do "geometry" on abstract vector spaces.
- & so much more!



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Feet back on the ground!

Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

Our story begins we the most important vector spaces: \mathbb{R}^n :

• $\vec{v} \in \mathbb{R}^n$ is a list of *n*-tuples:

$$\vec{v} = \langle v_1, v_2, v_3, \dots, v_n \rangle$$
 or $\vec{v} = \begin{vmatrix} v_2 \\ v_3 \\ \vdots \end{vmatrix}$

 $\left[v_1 \right]$

V_n



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Let's begin our journey together :-)