

## 2.8 Consequences of Invertibility

### *Theorem — The Really Big Theorem on Invertibility:*

The following conditions are equivalent for a linear operator  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ , with standard matrix  $[T] = A$  :

1.  $T$  is an invertible operator.
2.  $A$  is an invertible matrix.
3. The rref of  $A$  is  $I_n$ .
4.  $A$  is the product of elementary matrices.
5.  $T$  is one-to-one.
6.  $\ker(T) = \text{nullspace}(A) = \{\vec{0}_n\}$ .
7.  $\text{nullity}(T) = \text{nullity}(A) = 0$ .
8.  $T$  is onto.
9.  $\text{range}(T) = \mathbb{R}^n$ .
10.  $\text{rank}(T) = n$ .

11.  $\text{colspace}(A) = \mathbb{R}^n$ .
12. The columns of  $A$  are linearly independent.
13. The columns of  $A$  Span  $\mathbb{R}^n$ .
14. The columns of  $A$  form a basis for  $\mathbb{R}^n$ .
15.  $\text{rowspace}(A) = \mathbb{R}^n$ .
16. The rows of  $A$  are linearly independent.
17. The rows of  $A$  Span  $\mathbb{R}^n$ .
18. The rows of  $A$  form a basis for  $\mathbb{R}^n$ .
19. The homogeneous equation  $A\vec{x} = \vec{0}_n$  has only the trivial solution.
20. *For every  $n \times 1$  matrix  $\vec{b}$ , the system  $A\vec{x} = \vec{b}$  is **consistent**.*
21. *For every  $n \times 1$  matrix  $\vec{b}$ , the system  $A\vec{x} = \vec{b}$  has **exactly one solution**.*
22. *There exists an  $n \times 1$  matrix  $\vec{b}$ , such that the system  $A\vec{x} = \vec{b}$  has **exactly one solution**.*

## *One Sided Inverses*

Given  $A$ , we must find  $B$  so that:

$$AB = I_n \text{ and } BA = I_n$$

If  $B$  only satisfies the first equation, we call  $B$  a “right” inverse for  $A$ .

If  $B$  only satisfies the second equation we call  $B$  a “left” inverse for  $A$ .

Luckily, there's no need for this nonsense:

**Theorem:** An  $n \times n$  matrix  $A$  is invertible if and only if we can find an  $n \times n$  matrix  $B$  such that  $AB = I_n$  *or*  $BA = I_n$ . Thus, a “right” inverse is also a “left” inverse, and vice versa.

Proof: think of  $BA$  as a matrix representing the composition of two operators.

## *The Inverse of a Composition and Matrix Product*

**Theorem:** If  $T_1, T_2 : \mathbb{R}^n \rightarrow \mathbb{R}^n$  are both invertible operators, then  $T_2 \circ T_1$  is also invertible, and furthermore:

$$[T_2 \circ T_1]^{-1} = [T_1]^{-1}[T_2]^{-1}.$$

Analogously, if  $A$  and  $B$  are invertible  $n \times n$  matrices, then  $AB$  is also invertible, and furthermore:

$$(AB)^{-1} = B^{-1}A^{-1}.$$

The converse is also true!

**Theorem:** If  $T_1, T_2 : \mathbb{R}^n \rightarrow \mathbb{R}^n$  are operators and the *composition*  $T_2 \circ T_1$  is *invertible*, then *both*  $T_2$  and  $T_1$  are also invertible. Analogously if  $A$  and  $B$  are two  $n \times n$  matrices and the *product*  $AB$  is *invertible*, then *both*  $A$  and  $B$  are invertible.