

Chapter 1

The Canvas of Linear Algebra:

Euclidean Spaces and Subspaces

1.1 The Main Subject: Euclidean Spaces

Definition: An ordered n -tuple or vector is an ordered list of n real numbers:

$$\vec{v} = \langle v_1, v_2, \dots, v_n \rangle.$$

point (x_1, x_2, \dots, x_n)

Definition: The set of all possible n -tuples is called *Euclidean n -space*, denoted by the symbol \mathbb{R}^n :

$$\mathbb{R}^n = \{ \vec{v} = \langle v_1, v_2, \dots, v_n \rangle \mid v_1, v_2, \dots, v_n \in \mathbb{R} \}.$$

$$\mathbb{R}^n = \{ \vec{v} \}$$

$$\vec{v} \in \mathbb{R}^5, \vec{v} = \langle 3, 1, 0, -2, 5 \rangle$$

To distinguish real numbers from vectors, we will also refer to real numbers as scalars.

a real #

$$\vec{w} \in \mathbb{R}^5, \vec{w} = \langle 5, -2, 0, 1, 3 \rangle$$
$$\vec{v} \neq \vec{w}$$

Definition: Two vectors $\vec{u} = \langle u_1, u_2, \dots, u_n \rangle$ and $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$ from \mathbb{R}^n are **equal** if all of their components are pairwise equal, that is, $u_i = v_i$ for $i = 1..n$. Two vectors from *different* Euclidean spaces are *never* equal.

for $\vec{v} = \vec{w}$ we must \vec{v} & \vec{w} from same \mathbb{R}^n .
 $\vec{v} = \langle 1, 2, 3 \rangle \in \mathbb{R}^3$
 $\vec{w} = \langle 1, 2, 3, 0, 0, 0 \rangle \in \mathbb{R}^6$
 $\vec{v} \neq \vec{w}$

Definitions: Each \mathbb{R}^n has a special element called the **zero vector**, all of whose components are zero: $\vec{0}_n = \langle 0, 0, \dots, 0 \rangle$.

Every vector $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle \in \mathbb{R}^n$ has its own **additive inverse**, also known as its **negative**:

$$-\vec{v} = \langle -v_1, -v_2, \dots, -v_n \rangle.$$

Vector Arithmetic

Definitions: If $\vec{u} = \langle u_1, u_2, \dots, u_n \rangle$ and $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$ are vectors in \mathbb{R}^n , we define the **vector sum**:

$$\vec{u} + \vec{v} = \langle u_1 + v_1, u_2 + v_2, \dots, u_n + v_n \rangle,$$

and if $r \in \mathbb{R}$, we define the **scalar product**: (also called scalar multiplication)

$$r \cdot \vec{v} := r\vec{v} = \langle rv_1, rv_2, \dots, rv_n \rangle.$$

We will call the operation of finding the vector sum as **vector addition**, and the operation of finding a scalar product as **scalar multiplication**. We can also define **vector subtraction** by:

$$\vec{u} - \vec{v} = \vec{u} + (-\vec{v}) = \langle u_1 - v_1, u_2 - v_2, \dots, u_n - v_n \rangle.$$

not a def.

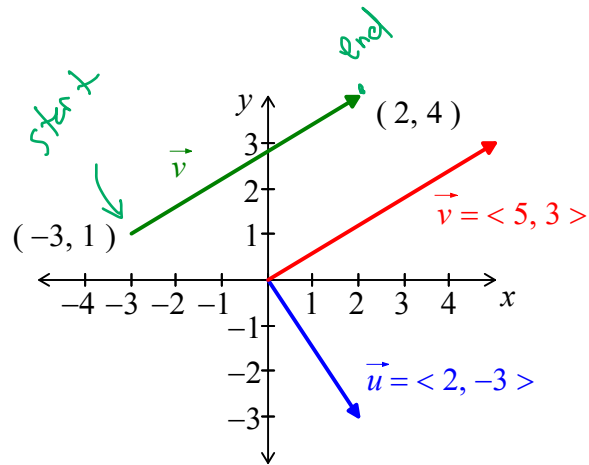
Theorem: The Multiplicative Property of the Scalar Zero:

Let $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle \in \mathbb{R}^n$. Then:

$$\underset{\substack{\uparrow \\ \text{scalar}}}{0} \cdot \vec{v} = \underset{\substack{\uparrow \\ \text{zero vector}}}{\vec{0}_n}.$$

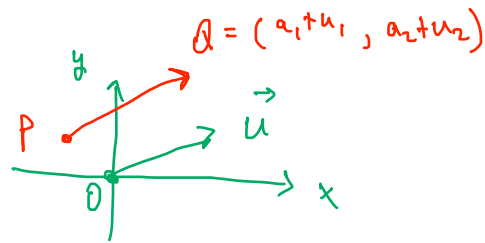
Pf $0 \cdot \langle v_1, v_2, \dots, v_n \rangle \stackrel{\substack{\uparrow \\ \text{def of} \\ \text{scalar mult}}}{=} \langle 0 \cdot v_1, 0 \cdot v_2, \dots, 0 \cdot v_n \rangle$
 $= \langle 0, 0, \dots, 0 \rangle$ (mult in \mathbb{R})
 $= \vec{0}_n.$ □

Visualizing Vectors from \mathbb{R}^2



Plotting Vectors in \mathbb{R}^2

Translating Vectors in \mathbb{R}^2



Theorem: Let $\vec{u} = \langle u_1, u_2 \rangle \in \mathbb{R}^2$, and $P(a_1, b_1)$ a point on the Cartesian plane. If \vec{u} is translated to P , then the head of \vec{u} will be located at $Q(a_2, b_2)$, where:

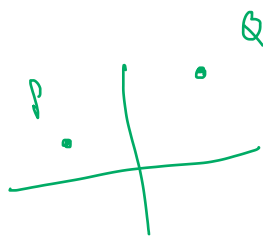
$$Q: \quad \underline{a_2 = a_1 + u_1}, \quad \text{and} \quad \underline{b_2 = b_1 + u_2}.$$

Conversely, if $P(a_1, b_1)$ and $Q(a_2, b_2)$ are two points on the Cartesian plane, then the vector $\vec{u} \in \mathbb{R}^2$ from P to Q is:

$$\vec{u} = \overrightarrow{PQ} = \langle a_2 - a_1, b_2 - b_1 \rangle.$$

stat end "Q - P"

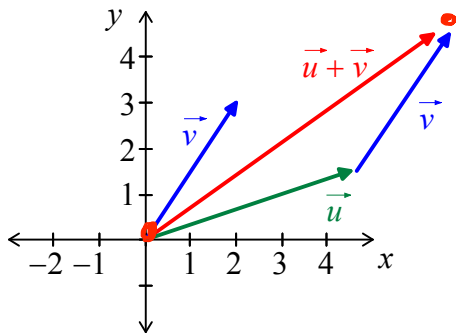
$$P = (x_1, y_1)$$
$$Q = (x_2, y_2)$$



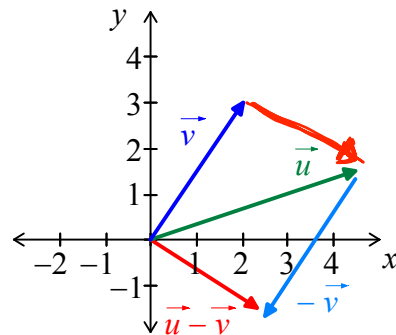
$$\vec{v} = \overrightarrow{PQ} = \langle x_2 - x_1, y_2 - y_1 \rangle$$

The Geometry of Vector Arithmetic in \mathbb{R}^2

Tip to Tail Rule



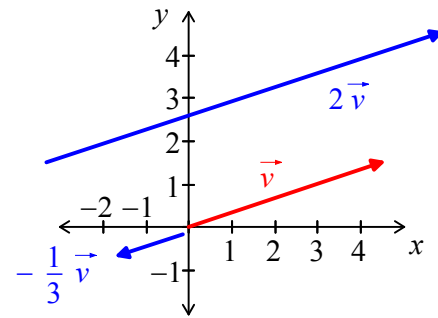
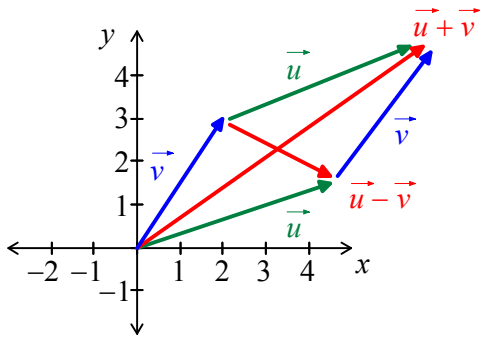
$\vec{u} \leftarrow \vec{v}$



Vector Addition and Subtraction in \mathbb{R}^2

The Parallelogram Principle;

Scalar Multiplication



Definition: Axiom for Parallel Vectors:

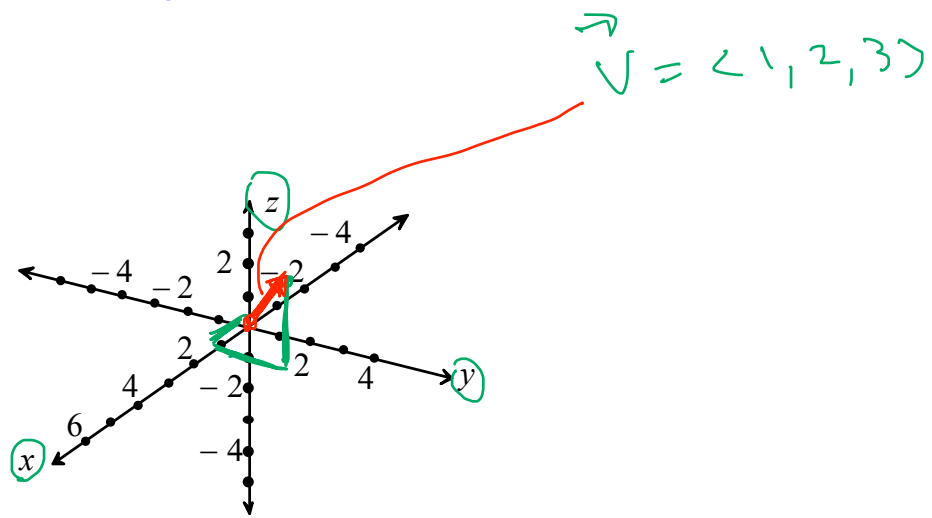
We say that two vectors $\vec{u}, \vec{v} \in \mathbb{R}^n$ are parallel to each other if there exists either $a \in \mathbb{R}$ or $b \in \mathbb{R}$ such that:

$$\vec{u} = a \cdot \vec{v} \quad \text{or} \quad \vec{v} = b \cdot \vec{u}.$$

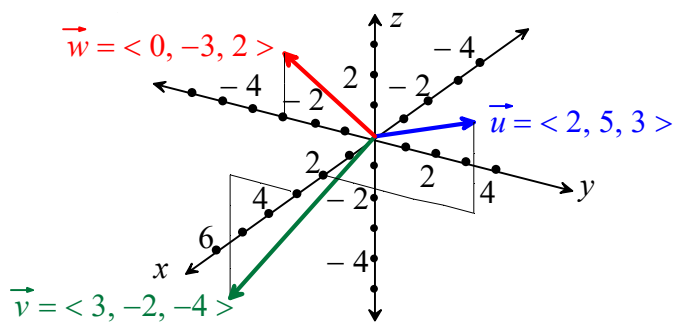
Consequently, this means that $\vec{0}_n$ is parallel to *all* vectors $\vec{v} \in \mathbb{R}^n$, since $\vec{0}_n = 0 \cdot \vec{v}$.

$\vec{0} = a \vec{v}$
Can we find $a \in \mathbb{R}$ to make this true?
Pick $a = 0$. 😊
So $\vec{0}$ is parallel to all vectors in \mathbb{R}^n .

Visualizing Vectors from \mathbb{R}^3



Cartesian Space



Plotting Vectors from \mathbb{R}^3

Translating Vectors in \mathbb{R}^3

Theorem: Let $\vec{u} = \langle u_1, u_2, u_3 \rangle \in \mathbb{R}^3$, and $P(a_1, b_1, c_1)$ a point in Cartesian space. If \vec{u} is translated to P , then the head of \vec{u} will be located at $Q(a_2, b_2, c_2)$, where:

$$a_2 = a_1 + u_1, \quad b_2 = b_1 + u_2, \quad \text{and} \quad c_2 = c_1 + u_3.$$

Conversely, let $P(a_1, b_1, c_1)$ and $Q(a_2, b_2, c_2)$ be two points in Cartesian space. Then the vector $\vec{u} \in \mathbb{R}^3$ from P to Q is:

$$\vec{u} = \overrightarrow{PQ} = \langle a_2 - a_1, b_2 - b_1, c_2 - c_1 \rangle.$$

Properties of Vector Arithmetic

Theorem — *Properties of Vector Arithmetic:*

If \vec{u} , \vec{v} , and \vec{w} are vectors in \mathbb{R}^n and r and s are scalars, then the following properties are true:

1. *The Closure Property of Vector Addition*

$$\vec{u} + \vec{v} \text{ is also in } \mathbb{R}^n.$$

(def)

2. *The Closure Property of Scalar Multiplication*

$$r\vec{u} \text{ is also in } \mathbb{R}^n.$$

(def)

3. *The Commutative Property of Vector Addition*

$$\vec{u} + \vec{v} = \vec{v} + \vec{u}.$$

to prove.

4. *The Associative Property of Vector Addition*

$$(\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w}).$$

to prove

5. *The Additive Identity Property*

$$\vec{0}_n + \vec{v} = \vec{v} = \vec{v} + \vec{0}_n.$$

to prove

$\forall \vec{v} \in \mathbb{R}^n$, $\exists -\vec{v} \in \mathbb{R}^n$ so that

6. The Additive Inverse Property

$$\vec{v} + (-\vec{v}) = \vec{0}_n = (-\vec{v}) + \vec{v}. \quad \text{to prove.}$$

7. The "Left" Distributive Property

$$(r+s)\vec{v} = r\vec{v} + s\vec{v}. \quad \text{to prove}$$

scalars vec vec vec

8. The "Right" Distributive Property

$$r(\vec{u} + \vec{v}) = r\vec{u} + r\vec{v}. \quad \text{to prove}$$

scal vec vec vec

9. The Associative Property of Scalar Multiplication

$$(rs)\vec{v} = r(s\vec{v}) = s(r\vec{v}). \quad \text{to prove}$$

10. The Unitary Property of Scalar Multiplication

$$1\vec{v} = \vec{v}. \quad \text{to prove}$$

scal vec vec

Proof of (9) Let $\vec{v} \in \mathbb{R}^n$ be arbitrary. Let $s, r \in \mathbb{R}$ (scalars).

WTS $(rs)\vec{v} = r(s\vec{v})$

Write $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$ where $v_i \in \mathbb{R}$, for $i=1, 2, \dots, n$.

Then

$$(rs)\vec{v} = (rs)\langle v_1, v_2, \dots, v_n \rangle$$

$$= \langle (rs)v_1, (rs)v_2, \dots, (rs)v_n \rangle \quad \text{(def of scal mult)}$$

$$= \langle r(sv_1), r(sv_2), \dots, r(sv_n) \rangle \quad \text{(A6 of } \mathbb{R} \text{)}$$

$$= r \langle sv_1, sv_2, \dots, sv_n \rangle \quad \text{(def scal mult)}$$

$$= r \langle s \langle v_1, v_2, \dots, v_n \rangle \rangle \quad \text{(def " ")}$$

$$= r(\vec{s}\vec{v}).$$



The Length of a Vector:

(this is extra structure!
not all vector spaces
have this!)

$$\vec{v} = \langle v_1, v_2, \dots, v_n \rangle, \quad \|\vec{v}\| = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

Definition: Let $\vec{v} = \langle v_1, v_2 \rangle \in \mathbb{R}^2$ and $\vec{w} = \langle w_1, w_2, w_3 \rangle \in \mathbb{R}^3$.

We define the *length* or *norm* or *magnitude* of these vectors as:

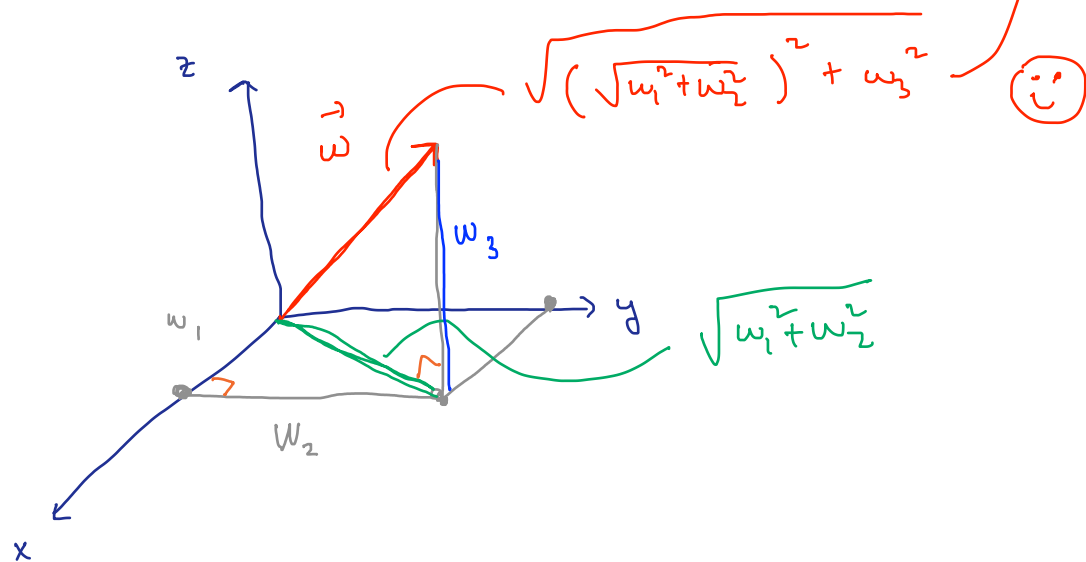
$$\|\vec{v}\| = \sqrt{v_1^2 + v_2^2}$$

$$\|\vec{w}\| = \sqrt{w_1^2 + w_2^2 + w_3^2}$$

length
of \vec{w}

We say that \vec{v} is a unit vector if $\|\vec{v}\| = 1$. Similarly, \vec{w} is a unit vector if $\|\vec{w}\| = 1$.

length 1.



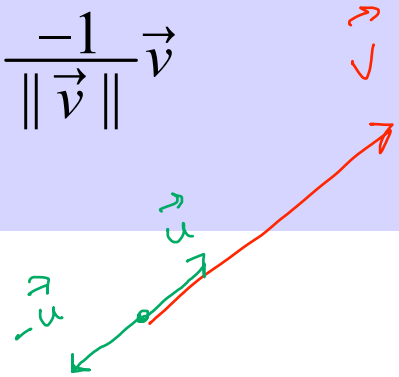
Theorem: For any scalar $k \in \mathbb{R}$ and vector $\vec{v} \in \mathbb{R}^2$ or \mathbb{R}^3 :

$$\|k\vec{v}\| = |k| \|\vec{v}\|.$$

Furthermore, $\|\vec{v}\| \geq 0$, and $\|\vec{v}\| = 0$ if and only if $\vec{v} = \vec{0}_2$ or $\vec{0}_3$. Consequently, if \vec{v} is a non-zero vector, then:

$$\vec{u}_1 = \frac{1}{\|\vec{v}\|} \vec{v} \quad \text{and} \quad \vec{u}_2 = \frac{-1}{\|\vec{v}\|} \vec{v}$$

are *unit vectors* parallel to \vec{v} .



Linear Combinations SUPER IMPORTANT!

list of vectors

$k \leq n$ or $k > n$

coeff. (scalars)

Definition: If $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \in \mathbb{R}^n$, and $x_1, x_2, \dots, x_k \in \mathbb{R}$, then the vector expression:

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_k \vec{v}_k$$

is called a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ with *coefficients* x_1, x_2, \dots, x_k .

Example: If $\vec{u} = \langle 5, -2, 3, -7 \rangle, \vec{v} = \langle -4, 2, 3, -6 \rangle$ and $\vec{w} = \langle 3, 0, -8, 3 \rangle$, then:

$$5\vec{u} - 3\vec{v} + 6\vec{w} =$$

On board.

Example: If $\vec{u} = \langle 5, -2, 4, 6 \rangle$ and $\vec{v} = \langle 1, -5, 2, -3 \rangle$, is it possible to express $\langle 11, 37, -2, 51 \rangle$ as a linear combination of \vec{u} and \vec{v} ?

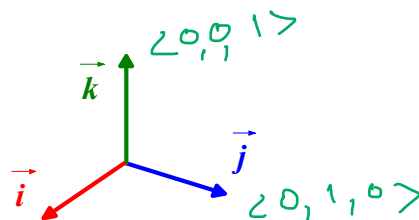
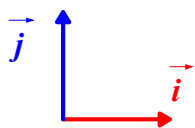
On board.

The Standard Basis Vectors

Definition: The *standard basis vectors* in \mathbb{R}^n are the vectors $\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n$ that have 0 in all components except the i^{th} component, which contains 1 :

$$\vec{e}_i = \langle 0, 0, \dots, 0, 1, 0, \dots, 0 \rangle.$$

i^{th} spot



The Standard Basis Vectors of \mathbb{R}^2 and \mathbb{R}^3



Theorem: Every vector $\vec{x} = \langle x_1, x_2, \dots, x_n \rangle \in \mathbb{R}^n$ can be expressed uniquely as a linear combination of the standard basis vectors:

$$\langle x_1, x_2, \dots, x_n \rangle = x_1 \vec{e}_1 + x_2 \vec{e}_2 + \dots + x_n \vec{e}_n.$$

Pf $\langle x_1, x_2, \dots, x_n \rangle = \langle x_1, 0, 0, \dots, 0 \rangle + \langle 0, x_2, x_3, \dots, x_n \rangle$
 $= x_1 \langle 1, 0, 0, \dots, 0 \rangle + \langle 0, x_2, x_3, \dots, x_n \rangle$
 $= x_1 \vec{e}_1 + \langle 0, x_2, x_3, \dots, x_n \rangle$

& continue like this.

$$= x_1 \vec{e}_1 + x_2 \vec{e}_2 + \dots + x_n \vec{e}_n. \quad \square$$

The Proof Template

Write the Theorem you are trying to prove, in its entirety.

Paraphrase the Theorem by identifying the *given conditions* and the *conclusion*:

We are given that:

The conclusion we want to reach is: or

We want to show that:

Write down the relevant *Definitions*:

The given conditions mean that:

The conclusions we want to reach mean that:

The notations in the Theorem mean:

Write down any relevant *Theorems* that are related to the given conditions or to the conclusion and try to connect everything in your template together in a complete proof.

Use the words and phrases:

let, consider, assume, suppose,

if, if and only if,

thus, therefore, this implies,

we can conclude that,

but, however,

we know that,

our goal is to show that,

according to this Theorem,

we get a contradiction,

let us form the contrapositive,

conversely . . . etc.

Practice!