

# 1.7 Subspaces of Euclidean Spaces; Basis and Dimension

**Definition:** A **subspace**  $W$  of  $\mathbb{R}^n$  is a non-empty subset of vectors of  $\mathbb{R}^n$  such that if  $\vec{u}, \vec{v} \in W$ , and  $r \in \mathbb{R}$ , then we also have:

$$\rightarrow \boxed{\vec{u} + \vec{v} \in W} \text{ and } \boxed{r \cdot \vec{v} \in W}. \leftarrow$$

We say  $W$  is **closed** under vector addition and scalar multiplication, and write:

$$\boxed{W \trianglelefteq \mathbb{R}^n}$$

$A \subseteq B$  a subset  $B$

$W \trianglelefteq \mathbb{R}^n$  subset  $\oplus$  closed

to indicate that  $W$  is a subspace of  $\mathbb{R}^n$ . We call  $\mathbb{R}^n$  the **ambient space** of  $W$ .

all subspaces contain  $\vec{0}$

**Theorem:** The zero vector  $\vec{0}_n$  is always a member of any subspace  $W \subseteq \mathbb{R}^n$ .

Pf let  $W \subseteq \mathbb{R}^n$ . By def,  $W \neq \emptyset$  so  $\vec{w} \in W$ .  
zero factor Thm:  $0\vec{w} = \vec{0}$ ,  $W$  is closed under scalar mult  
 $\vec{0} = 0\vec{w} \in W$ .  $\square$

**Definition/Theorem:** For any  $\mathbb{R}^n$ , there are two *trivial subspaces*:  
(1) the subspace  $\{\vec{0}_n\}$  consisting only of the zero vector, and (2) all of  $\mathbb{R}^n$  itself.

$$\{\vec{0}\} \subseteq \mathbb{R}^n \quad \mathbb{R}^n \subseteq \mathbb{R}^n$$

$\{\vec{0}\} \& \mathbb{R}^n$  trivial subspaces

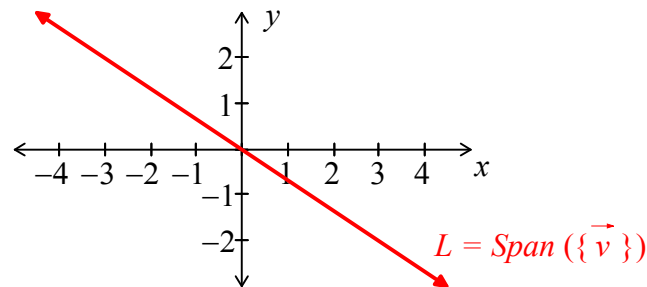
$$\{\vec{0}\} \subsetneq W \subsetneq \mathbb{R}^n$$

$\uparrow$  proper subspace.

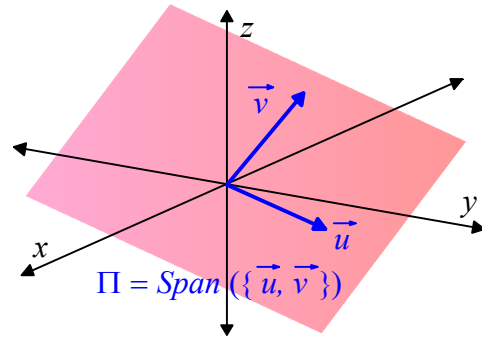
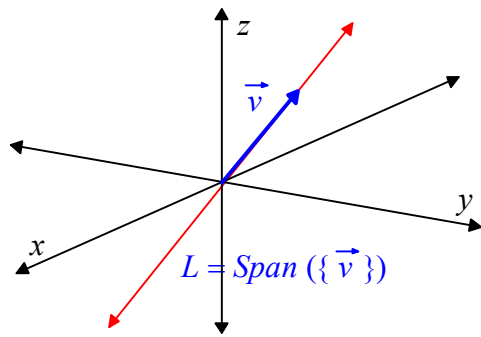
## *Span(S) as a Subspace*

**Theorem:** If  $S = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k\}$  is a non-empty set of vectors from  $\mathbb{R}^n$ , then  $W = \text{Span}(S)$  is a subspace of  $\mathbb{R}^n$ .

*Examples:*



A Line Through the Origin is a Subspace of  $\mathbb{R}^2$



Lines or Planes Through the Origin are Subspaces of  $\mathbb{R}^3$

# Basis for a Subspace

key concept



**Definition:** A **basis** for a non-zero subspace  $W \subseteq \mathbb{R}^n$  is a non-empty set of vectors  $B = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}$  which **Spans**  $W$  and is also **linearly independent**.

$$\text{Basis} = \text{LI} \oplus \text{Span}$$

**Example:** "Standard basis"  $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$  for  $\mathbb{R}^n$ .  $\square$

LI  $\checkmark$  Span  $\checkmark$   $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = x_1 \vec{e}_1 + \dots + x_n \vec{e}_n$

**Example:**

line through the origin  $\text{Span}(\{\vec{v}\})$ ,  $\vec{v} \neq \vec{0}$ .  
 $\hookrightarrow$  subspace

plane through the origin  $\text{Span}(\{\vec{u}, \vec{v}\})$   $\vec{u} \nparallel \vec{v}$   
 $\hookrightarrow$  subspace.

## A Basis for Span(S)

**Theorem:** The set  $B = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}$  is a basis for  $W = \text{Span}(B)$  if and only if  $B$  is linearly independent.

$$\left. \begin{array}{l} (\Rightarrow) \\ B \text{ basis} \\ \& W = \text{Span}(B) \end{array} \right\} \rightarrow B \text{ is LI,}$$

$$\left. \begin{array}{l} (\Leftarrow) \\ B \text{ is LI} \\ \& \text{Span}(B) = W \end{array} \right\} \Rightarrow \text{def of basis.}$$

**Example:** Suppose  $S = \{\langle 1, 7, 3, -8, 2 \rangle, \langle 4, -2, 5, 3, -4 \rangle\}$ .

$$\text{LI or LD?} \quad \vec{v} = t \vec{w}$$

$$\vec{u} \parallel \vec{v} \quad \left. \begin{array}{l} 1 = 4t \\ 7 = -2t \end{array} \right\} \text{contradiction!}$$

not parallel! LI!

$S$  forms a basis for  $W = \text{Span}(\vec{v}, \vec{w})$ .  
↑  
subspace

★ USEFUL!!

**Theorem — The Minimizing Theorem (Basis for Span(S) Version):**

Suppose  $S = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}$  and  $W = \text{Span}(S)$ . If  $A = [\vec{w}_1 \ \vec{w}_2 \ \dots \ \vec{w}_k]$ , and  $R$  is the rref of  $A$ , then the columns of  $A$  corresponding to the leading columns of  $R$  form a **basis** for  $W$ .

MAGIC!!!

**Example:** Suppose  $W = \text{Span}(S)$ , where:

$$S = \{\vec{w}_1, \vec{w}_2, \vec{w}_3\}$$

$$= \{\langle 11, -13, -8, 17 \rangle, \langle -4, 7, 3, -6 \rangle, \langle 10, -5, -7, 16 \rangle\}.$$

$$A = \begin{bmatrix} 11 & -4 & 10 \\ -13 & 7 & -5 \\ -8 & 3 & -7 \\ 17 & -6 & 16 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

↑ LI
↑ LI
↑ LD

\* note we haven't done this before!

$A$  is not a SOE! Purely the into of  $S$ ,

\*  $\{\vec{w}_1, \vec{w}_2\}$  is LI

\*  $\text{Span}(\vec{w}_1, \vec{w}_2) = \text{Span}(S) = W$

SO  $\{\vec{w}_1, \vec{w}_2\}$  is a basis for  $W$ .

$$\text{col } 3 = 2 \text{ col } 1 + 3 \text{ col } 2$$

$$\begin{bmatrix} 2 \\ 3 \\ 0 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

## Constructing a Basis for Any Subspace

~~\*\*\*~~ IMPORTANT RESULT ~~\*\*\*~~ DEEP

### Theorem — Existence of a Basis Theorem:

If  $W$  is any non-zero subspace of  $\mathbb{R}^n$ , then there exists a basis  $B = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}$  for  $W$ . In other words, we can write:

$$W = \text{Span}(B) = \text{Span}(\{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}),$$

where  $B$  is a linearly independent set that Spans  $W$ . Furthermore, we must have  $k \leq n$ .

Pf Assume  $W \neq \emptyset$ , pick some  $\vec{w}_1 \in W$ . Can assume  $\vec{w}_1 \neq \vec{0}$ .

Step 1  $S_1 = \{\vec{w}_1\}$ . Since  $\vec{w}_1 \neq \vec{0}$ ,  $\{\vec{w}_1\}$  is LI.

So if  $\text{Span}(S_1) = W$ , we're done. (since  $S_1$  is a basis for  $W$ )

Step 2 Otherwise, there exist  $\vec{w}_2 \in W \setminus \text{Span}(S_1)$

In particular,  $\vec{w}_2 \neq \vec{0}$ .

$$S_2 = \{\vec{w}_1, \vec{w}_2\}.$$

So by the Extension Theorem (§1.6),  $S_2$  is LI.

So if  $\text{Span}(S_2) = W$ , we're done (since  $S_2$  is a basis)

In general, we can continue in this manner.



## Theorem — The Subspaces of Euclidean 2-Space and 3-Space:

The only subspaces of  $\mathbb{R}^2$  are:

- (a) the zero subspace  $\{\vec{0}_2\}$ ,
- (b) the *lines* through the origin, and
- (c) all of  $\mathbb{R}^2$ .

Similarly, the only subspaces of  $\mathbb{R}^3$  are:

- (a) the zero subspace  $\{\vec{0}_3\}$ ,
- (b) the *lines* through the origin,
- (c) the *planes* through the origin, and
- (d) all of  $\mathbb{R}^3$ .

$\mathbb{R}$

•  $\{0\}$

• ?

•  $\mathbb{R}$

no proper  
subspaces!

$\mathbb{R}^2$

•  $\{\vec{0} = \langle 0, 0 \rangle\}$

•  $W =$  lines through origin

•  $\mathbb{R}^2$

$\mathbb{R}^3$

•  $\vec{0}$

{

- lines thru origin
- planes thru origin

}

•  $\mathbb{R}^3$

# The Dimension of a Subspace

the actual "theorem" part

## Theorem/Definition — The Dimension of a Subspace:

If  $B$  and  $B'$  are any two bases for the same non-zero subspace  $W \subseteq \mathbb{R}^n$ , then  $B$  and  $B'$  contain exactly the same number of vectors. We call this number the dimension of  $W$ , and we write  $\dim(W) = k$ . We also say that  $W$  is  $k$ -dimensional.

We agreed that the trivial subspace  $\{\vec{0}_n\}$  does *not* have a basis. By convention,  $\dim(\{\vec{0}_n\}) = 0$ .

Conversely,  $\dim(W)$  is a *positive integer* for a *non-zero* subspace  $W$ .

$$B = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_k\} \text{ basis of } W$$

↑  
dimension.

Notation  $\#B = \|B\| = \text{Card}(B) = \# \text{ of vectors in } B$

$\{\vec{0}\}$ , basis for this?  $B = \emptyset$ .  $\text{Card}(B) = 0$ .  
technicality  
 $\{\vec{0}\}$  is L.D.  $\rightarrow$  can't be a basis.

*Example:*  $\dim(\mathbb{R}^n) = ?$

*Example:*

line through the origin

plane through the origin

**Example:**  $W = \text{Span}(S)$ , where:

$$S = \{ \vec{w}_1, \vec{w}_2, \vec{w}_3 \} \\ = \left\{ \begin{array}{l} \langle 11, -13, -8, 17 \rangle, \langle -4, 7, 3, -6 \rangle, \\ \langle 10, -5, -7, 16 \rangle \end{array} \right\}.$$

ambient space?  $\mathbb{R}^4$

maximum possible dimension? 3

basis?  $\mathcal{B}$

actual dimension? 2

test if  $S$  is LI or LD:

$\begin{bmatrix} 11 & -4 & 10 \\ -13 & 7 & -5 \\ -8 & 3 & -7 \\ 17 & -6 & 16 \end{bmatrix}$	$\xrightarrow{\text{RREF}}$	$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
		<p>↑ LI    ↑ LI    ↑ LD</p>
		<p>&amp; Spanning original</p>

Basis

$$\mathcal{B} = \left\{ \begin{bmatrix} 11 \\ -13 \\ -8 \\ 17 \end{bmatrix}, \begin{bmatrix} -4 \\ 7 \\ 3 \\ -6 \end{bmatrix} \right\} \text{ is a basis}$$

*Example:*  $W = \text{Span}(S)$ , where:

$$S = \{ \langle 3, -2, 5, 4, 1, -6 \rangle, \langle 5, -3, 6, 3, 2, -8 \rangle, \\ \langle -11, 5, -2, 11, -6, 8 \rangle, \\ \langle -2, 1, -4, -2, 0, 6 \rangle, \langle -4, 1, -1, 7, -1, 6 \rangle \}.$$

ambient space?

maximum possible dimension?

$$A = \begin{bmatrix} 3 & 5 & -11 & -2 & -4 \\ -2 & -3 & 5 & 1 & 1 \\ 5 & 6 & -2 & -4 & -1 \\ 4 & 3 & 11 & -2 & 7 \\ 1 & 2 & -6 & 0 & -1 \\ -6 & -8 & 8 & 6 & 6 \end{bmatrix}, \text{ with rref:}$$

$$R = \begin{bmatrix} 1 & 0 & 8 & 0 & 5 \\ 0 & 1 & -7 & 0 & -3 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$