

What is Linear Algebra? A Bird's Eve View

Dr. Jorge Eduardo Basilio

Department of Mathematics & Computer Science Pasadena City College

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What is Linear Algebra?

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Beauty & Importance

Vectors

Systems of Equations

Birth of Linear Algebra

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Back to Mathematician vectors

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What is Linear Algebra? Beauty & Importance



What is Linear Algebra?

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A beautiful subject . . . why?

real mathematical theory

- (likely) your first love (er...exposure) of proofs
- moves effortlessly from lines, to planes, to hyperplanes, to n-dimensional space \mathbb{R}^n
- you'll learn to "see" 12-dimensional space
- Ditch geometry, but don't ditch geometry!
- theory with purpose! So many APPs (applications)
- Enormous importance! Maybe even greater than Calculus!

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What is Linear Algebra?

LAPs (Linear Algebra Applications):

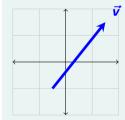
- ullet Economics: Leontief model of Economics (1950s Harvard professor o won Nobel prize in Econ)
- Physics: so many! A few are...
 - vectors in 2D, 3D, and higher dimensions
 - Forces, Electrice Fields, Magnetic Fields, ...
 - Quantum Mechanics (uses ∞-dimensional LA)
- Data Science: stats + LA + Calc + programming
- Engineering:
- MATH duh!
 - most (all?) mathematical courses use LA in some way
- But ... we'll not study any of these applications in detail INSTEAD we'll lay the foundations for these APPs



We start with vectors. Vectors according to...

Physicists

"something with a magnitude & direction"



Computer Scientists "a list (or array) of

numbers"

$$ec{v} = egin{bmatrix} 1 \ 2 \ -1 \ 0 \ -5 \end{bmatrix}$$

Mathematicians

"an element of a vector space"



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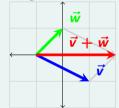
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Properties of vectors

Physicists

"something with a magnitude & direction"



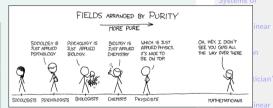
Computer Scientists

"a list (or array) of numbers"

$$\vec{v} + \vec{w} = \begin{bmatrix} 1 \\ 2 \\ -1 \\ 0 \\ -5 \end{bmatrix} + \begin{bmatrix} 3 \\ 0 \\ 2 \\ -2 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 1 \\ -2 \\ -1 \end{bmatrix}$$

Mathematicians

"an element of a vector space"



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Mathematician's view abstracts the properties shared by many different objects studied over a long period of time. So, mathematician's care **only** about structure of objects not superficially what they look like.

- Vectors live in vector spaces. Vector spaces are collections of objects that satisfy many properties. The most important are:
- 7/n
- lacksquare \mathbb{Q}^n
- Rⁿ
- lacksquare \mathbb{C}^n
- $\mathbb{M}_{n \times n}$ space of all $n \times n$ matrices

- ullet $P(\mathbb{R},\mathbb{R})$ space of all polynomials
- $C([a,b],\mathbb{R})$ space of all continuous functions
- $C^{\infty}([a,b],\mathbb{R})$ space of all differentiable functions
- $\ell_\infty(\mathbb{R})$ space of all sequences
- space of all power series

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Mathematician's care **only** about structure of objects not superficially what they look like.

- What do these examples have in common?
- Addition: there is a "natural" way to define how to add two objects
- Scalar Multiplication: there is a "natural" what to define what multiplying an object by a real number α
- Example: using computer scientist's concept of vector, we can define "addition" and "scalar multiplication" via components

$$\begin{bmatrix} 1 \\ 2 \\ -1 \\ 0 \end{bmatrix} + \begin{bmatrix} 3 \\ 0 \\ 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 1 \\ -2 \end{bmatrix} \quad \text{and} \quad \alpha \cdot \begin{bmatrix} 4 \\ 2 \\ 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 4\alpha \\ 2\alpha \\ \alpha \\ -2\alpha \end{bmatrix}$$

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What is Linear Algebra? ... matrices?



Mathematician's care **only** about structure of objects not superficially what they look like.

- Addition: there is a "natural" way to define how to add two objects
- Scalar Multiplication: there is a "natural" what to define what multiplying an object by a real number α
- Example: For matrices we define "addition" and "scalar multiplication" via components as well

$$\begin{bmatrix} 1 & -7 \\ 2 & 8 \\ -1 & -3 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 3 & 0 \\ 0 & 1 \\ 2 & -5 \\ -2 & 6 \end{bmatrix} = \begin{bmatrix} 4 & 6 \\ 2 & -1 \\ 1 & -8 \\ -2 & 8 \end{bmatrix} \text{ and } \alpha \cdot \begin{bmatrix} 4 & 6 \\ 2 & -1 \\ 1 & -3 \\ -2 & 8 \end{bmatrix} = \begin{bmatrix} 4\alpha & 6\alpha \\ 2\alpha & -\alpha \\ \alpha & -3\alpha \\ -2\alpha & 8\alpha \end{bmatrix}$$

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What is Linear Algebra?

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Systems of Equations

In many ways, all of linear algebra boils down to solving a system of equations.

•
$$\begin{cases} x + 2y + 3z = 4 \\ -x + y - 5z = 0 \\ 2x - y - z = -1 \end{cases} \iff \begin{bmatrix} 1 & 2 & 3 \\ -1 & 1 & -5 \\ 2 & -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -1 \end{bmatrix}$$

"column picture"

$$\iff x \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + y \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} + z \begin{bmatrix} 3 \\ -5 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ -1 \end{bmatrix}$$



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System of equations. A simple example.

$$\bullet \begin{cases}
x - y &= -2 \\
x + 2y &= 1
\end{cases} \Longleftrightarrow \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \Longleftrightarrow \boxed{A\vec{x} = \vec{b}}$$

- "row picture" $\begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ intersection of two lines
- "column picture" $x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ linear combinations

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System of equations. A simple example.

$$\begin{cases}
x - y &= -2 \\
x + 2y &= 1
\end{cases}
\iff
\begin{bmatrix}
1 & -1 \\
1 & 2
\end{bmatrix}
\begin{bmatrix}
x \\
y
\end{bmatrix}
=
\begin{bmatrix}
-2 \\
1
\end{bmatrix}
\iff
\boxed{A\vec{x} = \vec{b}}$$

• "row picture" $\begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ intersection of two lines

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System of equations. A simple example.

$$\bullet \begin{cases}
x - y &= -2 \\
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\end{cases} \Longleftrightarrow \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \Longleftrightarrow \boxed{A\vec{x} = \vec{b}}$$

• "column picture" $x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ linear combinations

Geometry of linear combinations...

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System of equations.

- Okay, that was easy. So what?
- We need to solve LARGE systems.
- A system with *n* variables and *n* unknowns:

$$\begin{cases}
a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1 \\
a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2 \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
a_{n1}x_1 + a_{n2}x_2 + a_{n3}x_3 + \dots + a_{nn}x_n = b_n
\end{cases}
\Leftrightarrow A\vec{x} = \vec{b}$$

$$\iff \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

Note: n = 1000 is considered "small" nowadays

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Systems of Equations

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System of equations.

- A system with *n* variables and *n* unknowns:
- "Row picture" $\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$

Row picture = intersection of n hyperplanes

• "Column picture"
$$x_1 \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix} + x_2 \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{n2} \end{bmatrix} + \cdots + x_n \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{nn} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

Row picture = what linear combination of columns equals \vec{b} ?

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Recall the simple example.

•
$$\begin{cases} x - y &= -2 \\ x + 2y &= 1 \end{cases} \iff \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \iff \boxed{A\vec{x} = \vec{b}}$$

- "column picture" $x \begin{bmatrix} 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ linear combinations
- Notation: Let $\vec{v} = \text{Col } 1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\vec{w} = \text{Col } 2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, and $\vec{b} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$
- Recall: we found that $(-1)\vec{v} + (1)\vec{w} = \vec{b}$ (i.e. x = -1, y = 1).

The birth of linear algebra is to consider <u>ALL</u> possible linear combinations of \vec{v} and \vec{w} !!!!

That is,
$$\{x_1\vec{v} + x_2\vec{w} \mid x_1, x_2 \in \mathbb{R}\} = \text{span}(\vec{v}, \vec{w})$$

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The birth of linear algebra is to consider <u>ALL</u> possible linear combinations of \vec{v} and \vec{w} !!!!

That is,
$$\{x_1\vec{v} + x_2\vec{w} \mid x_1, x_2 \in \mathbb{R}\} = \text{span}(\vec{v}, \vec{w})$$

- Notation: Let $\vec{v} = \text{Col } 1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\vec{w} = \text{Col } 2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, and $\vec{b} = \begin{bmatrix} a \\ b \end{bmatrix}$
- So, we can write $A = [\vec{v} \mid \vec{w}]$
- Can we solve this for any $a, b \in \mathbb{R}$?
- YES!
- Why? Because all linear combinations of \vec{v} and \vec{w} will fill the entire plane!!!
- Higher dimensions is much more interesting :-)

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To summarize:

• A major problem in linear algebra is to solve a system of equations:

$$A\vec{x} = \vec{b}$$

- This is the same thing as asking: when is \vec{b} a linear combination of the columns vectors of A (i.e. in the span)?
- This is solved using Gauss-Jordan elimination. A clever algorithm that's embarrassingly simple (in principle)

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- Next, we generalize our situation to systems of equations with an uneven number of equations and unknowns.
- If we let m=# equations and n=# unknowns, we'd like to study

$$\begin{cases}
a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1 \\
a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2 \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n = b_m
\end{cases}
\iff A\vec{x} = \vec{b}$$

- New phenomena can occur now.
- **Imagine** What if we have two 5-dimensional vectors \vec{v} and \vec{w} . Can all their linear combinations fill-up all of 5-dimensional space?
- NO! There's too few vectors
- What about five, 5-dimensional vectors? It depends....they must all live in their separate planes...

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- New phenomena can occur now.
- Imagine What if we have two 5-dimensional vectors \vec{v} and \vec{w} . Can all their linear combinations fill-up all of 5-dimensional space?
- NO! There's too few vectors
- What about five, 5-dimensional vectors? It depends....they must all live in their separate planes...
- This introduces the important idea of independence. That is, we say a collection of vectors are independent if they "fill up" space as much as possible (a more precise definition will be given later).
- Remarkably, all this information is encoded in the matrix A associated to the SOE.

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Remarkably, all this information is encoded in the matrix A associated to the SOE.

- By studying the structure of A, we can answer many fundamental questions related to a SOE.
- There's four fundamental "subspaces" associated to A
 - Column Space (all linear combinations of columns of A)
 - Row Space (all linear combinations of rows of A)
 - Null space of A
 - Null space of A^T

Gauss-Jordan Elimination



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- Meanwhile: almost every problem in linear algebra is solved (one way or another with) Gauss-Jordan Elimination (GJE).
- The method of GJE is used for
 - Checking if a list of vectors are independent
 - Solving SOEs: $A\vec{x} = \vec{b}$
 - Checking if a vector \vec{b} is in the span of of a list of other vectors (= space of all linear combinations)
 - Finding the column space of a matrix
 - Finding the row space of a matrix
 - Finding the rank of a matrix
 - Basically everything in Linear Algebra :-)

Back to Mathematician's vectors



Recall: the mathematician's view of "vectors:" objects you can ADD and scalar multiply. We can do that with matrices!

Addition

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} & b_{13} & \cdots & b_{1n} \\ b_{21} & b_{22} & b_{23} & \cdots & b_{2n} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ b_{n1} & b_{n2} & b_{n3} & \cdots & \vdots \\ b_{n1} & b_{n2} & b_{n3} & \cdots & b_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & a_{13} + b_{13} & \cdots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & a_{23} + b_{23} & \cdots & a_{2n} + b_{2n} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ a_{n1} + b_{n1} & a_{n2} + b_{n2} & a_{n3} + b_{n3} & \cdots & a_{nn} + b_{nn} \end{bmatrix}$$

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Recall: the mathematician's view of "vectors:" objects you can ADD and scalar multiply. We can do that with matrices!

Scalar Multiplication

$$\alpha \begin{bmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \mathbf{a}_{13} & \cdots & \mathbf{a}_{1n} \\ \mathbf{a}_{21} & \mathbf{a}_{22} & \mathbf{a}_{23} & \cdots & \mathbf{a}_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \mathbf{a}_{n1} & \mathbf{a}_{n2} & \mathbf{a}_{n3} & \cdots & \mathbf{a}_{nn} \end{bmatrix} = \begin{bmatrix} \alpha \mathbf{a}_{11} & \alpha \mathbf{a}_{12} & \alpha \mathbf{a}_{13} & \cdots & \alpha \mathbf{a}_{1n} \\ \alpha \mathbf{a}_{21} & \alpha \mathbf{a}_{22} & \alpha \mathbf{a}_{23} & \cdots & \alpha \mathbf{a}_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \alpha \mathbf{a}_{n1} & \alpha \mathbf{a}_{n2} & \alpha \mathbf{a}_{n3} & \cdots & \alpha \mathbf{a}_{nn} \end{bmatrix}$$



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What is Linear Algebra?

Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that map one vector space to another.



Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

- We've briefly discussed vectors and vector spaces (the set/collection of all vectors).
- Notation: \vec{v} a vector. V the vector space that collects all vectors. We can write $\vec{v} \in V$.
- The structure of *V* is easy to describe:
 - "closure under addition": if $\vec{v}, \vec{w} \in V$, then $\vec{v} + \vec{w} \in V$
 - "closure under scalar multiplication:" if $\vec{v}, \vec{w} \in V$, and $a, b \in \mathbb{R}$ are arbitrary, then $a\vec{v} + b\vec{w} \in V$
- The second bullet is what "linear structure" means in an abstract sence.

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Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

- The other major goal, once we understand what vector spaces are (and have studied many examples), is to study maps (or functions) between two vector spaces.
- Notation: $L:V\to W.$ If $\vec{v}\in V$, then $T(\vec{v})\in W$
- L because we want to study "linear transformations"
- The structure of *L* is easy to describe:
 - "additive structure:" if $\vec{v}, \vec{w} \in V$, then $T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w})$
 - "multiplicative structure:" if $\vec{v} \in V$ and $a \in \mathbb{R}$, then $T(a\vec{v}) = aT(\vec{v})$

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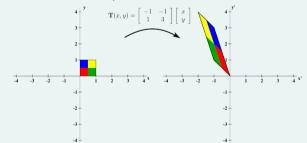
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- Example in 1*D*: L(x) = 2x. This is a linear map from $V = \mathbb{R}$ to $W = \mathbb{R}$.
 - L(x+y) = 2(x+y)=2x+2y = L(x)+L(y)
 - L(ax) = 2(ax) = a(2x) = aL(x)
- Example in 2D: $L(\langle x,y\rangle)=\langle -y,x\rangle$. This is a linear map from $V=\mathbb{R}^2$ to $W=\mathbb{R}^2$ (from 2D plane to another 2D plane)



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Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

There's so much more to this story!

- Add more structure: inner-products (measure length of vectors and angles). Can do "geometry" on abstract vector spaces.
- & so much more!

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Feet back on the ground!



Linear Algebra is...

The study of vector spaces, their structure, and the linear transformations that *map* one vector space to another.

Our story begins we the most important vector spaces: \mathbb{R}^n :

• $\vec{v} \in \mathbb{R}^n$ is a list of *n*-tuples:

$$\vec{v} = \langle v_1, v_2, v_3, \dots, v_n \rangle$$
 or $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ \vdots \\ v_n \end{bmatrix}$

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Let's begin our journey together :-)